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ABSTRACT

A new approach is presented to measure the length distribution of dispersed single-walled carbon nanotubes (SWCNT). In this method, the diffusive trajectories of individual SWCNTs in solution are reconstructed from high frame rate video stacks. These trajectories allow the estimation of two key statistics for the SWCNTs: their translational diffusion coefficient and the autocorrelation time of their fluorescence intensity. We show that the autocorrelation time is a measure of the rotational diffusion coefficient of the SWCNTs and that the length of the SWCNTs can be estimated either from the rotational diffusion coefficients alone or by combining translational and rotational diffusion coefficients. Moreover, this last estimate does not require knowledge of the solution viscosity or of the SWCNT hydrodynamic diameter.

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I. INTRODUCTION

Single-walled carbon nanotubes (SWCNTs) are used in a myriad of applications, including for enhancing the properties of materials,¹ electronics,² light sources,³ bioimaging,⁴ or biomedicine,⁵ to name a few. The inherent polydispersity of SWCNTs in their length is a major issue, as different lengths are often preferred for specific applications. While several length sorting methods have been proposed to reduce this dispersity, it remains difficult to estimate the full distribution of SWCNT lengths in a simple, quantitative, and high yield method.

Atomic force microscopy imaging allows for direct observation of SWCNT length,^{6,7} but it is a time-consuming method that requires specialized equipment and skills. In the context of video microscopy experiments, a method that allows the measurement of SWCNT lengths with no additional equipment is highly desirable. The “Length Analysis by Nanotube Diffusion” (LAND) method, proposed by Streit and co-workers,⁸ is such a method. Briefly, a LAND experiment consists of imaging single (semiconducting) SWCNTs freely diffusing in an aqueous solution on a fluorescence microscopy setup. Standard localization and linking algorithms allow the reconstruction

of continuous SWCNT trajectories.^{9,10} The diffusion coefficients of SWCNTs are estimated from these trajectories,^{11–13} and their lengths are derived from the diffusion coefficients.

Although LAND is in appearance straightforward, the method requires an accurate estimate of the solution viscosity η , as the diffusion coefficient is inversely proportional to it. Inaccurate knowledge of the solution viscosity can lead to systematic errors. In particular, the original report and applications of the LAND method reported an up to twofold discrepancy between the SWCNT lengths estimated by LAND and the optically measured length when considering only SWCNTs so long that their length could be directly measured on the video frames;^{8,14,15} this discrepancy was explained as arising from the extreme thinness of the sample-holding chamber¹⁶ and corrected by replacing the bulk solution viscosity by an effective viscosity whose measurement required a separate calibration. Additionally, for short SWCNTs, which diffuse very quickly in water, high-viscosity solutions (glucose or sucrose solutions, or water–glycerol mixtures) may be used to slow down diffusion and simplify SWCNT tracking;^{14,15} however, the viscosity of such solutions depends strongly on the mixture fractions and on the temperature,^{17,18} which are typically

not precisely controlled. For example, between 16°C and 32°C, the viscosity of a 2:1 v/v water–glycerol mixture decreases twofold.¹⁹ Therefore, it would be desirable to be able to make LAND-style analyses independent of the sample viscosity—not only independent of the bulk sample viscosity, which could be measured separately, but also, and more importantly, independent of the effective *in situ* viscosity. The LAND method also depends on an estimate of the nanotube hydrodynamic diameter. Again, this diameter can typically only be approximated, which is a significant additional source of errors.

Here, we show that any LAND experiment performed at a sufficiently high frame rate already contains additional information that allows estimation of SWCNT length independently of the solution viscosity and nearly independently of the nanotube hydrodynamic diameter. Specifically, when the SWCNTs are localized, a by-product of the fitting routine is the SWCNT fluorescence intensity. Here, we show that fluctuations of this intensity along the trajectory report on the SWCNT rotational diffusion coefficient and that SWCNT length can be estimated either from intensity fluctuations alone or by combining translational diffusion and intensity fluctuations; most interestingly, this last method does not require knowledge of the solution viscosity or of the SWCNT hydrodynamic diameter.

II. THEORY

A. Translational and rotational diffusion

In a viscous medium, the two-dimensional mean-square displacement of a diffusing SWCNT,

$$\text{MSD}_T(t) = \frac{1}{T-t} \sum_{i=1}^{T-t} (\mathbf{r}_{i+t} - \mathbf{r}_i)^2, \quad (1)$$

(where T is the number of frames in the movie stack and \mathbf{r} the 2D projection of the position vector of the SWCNT) grows linearly with the time lag t ,

$$\text{MSD}_T(t) = 4D_T t, \quad (2)$$

where D_T is the translational diffusion coefficient. In the presence of a localization error with standard deviation σ and motion blur over the exposure time t_E , the empirically measured mean-square displacement is

$$\text{MSD}_T(t) = 4D_T t + 4\sigma^2 - \frac{4}{3}D_T t_E. \quad (3)$$

It is well established that due to the finite length of the movies stacks, the optimal estimator for D_T consists of computing the slope in an unweighted linear fit for t vs $\text{MSD}(t)$ for the first few time lags.^{8,11}

The diffusion of SWCNTs shorter than 3 μm can be approximated as one of rigid rods^{20,21} for which the translational diffusion coefficient is given by

$$D_T = \frac{kT}{3\pi\eta L} [\log p + X_T(p)], \quad (4)$$

where k is the Boltzmann constant, T the temperature, η the viscosity of the medium, L the length of the SWCNT, and $p = L/d$ its hydrodynamic aspect ratio (the ratio of its length to its hydrodynamic diameter d); $X_T(p)$ is a finite-length correction term,²²

$$X_T(p) \approx 0.38 - \frac{1.16}{\sqrt{p}} + \frac{1.77}{p} - \frac{0.14}{p^2} + \frac{0.55 \log p}{p} - \frac{0.10 \log p}{p^2}. \quad (5)$$

Equation (4) implicitly defines the LAND length estimate, L_T , as a function of the translational diffusion coefficient D_T .

The mean-square angular displacement of a diffusing SWCNT, $\text{MSD}_R(t)$, also grows linearly with time at short time lags,

$$\text{MSD}_R(t) = \frac{1}{T-t} \sum_{i=1}^{T-t} (\Delta\alpha_{i,i+t})^2 = 4D_R t, \quad (6)$$

where $\Delta\alpha_{i,i+t}$ is the change in the direction in which the SWCNT points between times i and $i+t$ and D_R is the rotational diffusion coefficient. Similarly to D_T , D_R can be expressed as

$$D_R(t) = \frac{3kT}{\pi\eta L^3} [\ln p + X_R(p)], \quad (7)$$

where $X_R(p)$ is again a finite-length correction term,²²

$$X_R(p) \approx -0.49 - \frac{1.18}{\sqrt{p}} + \frac{3.17}{p} - \frac{3.29}{p^2} + \frac{3.69}{p^3} - \frac{1.72}{p^4}. \quad (8)$$

Assuming that an estimate of D_R is available, then, similarly to the translational case, Eq. (7) implicitly defines a length estimate L_R based on the rotational diffusion coefficient D_R .

Taken together, these expressions suggest a third method for obtaining the length of the SWCNT from experimental estimates of its linear and rotational diffusion coefficients. Specifically, we have

$$\left(\frac{\log p + X_T(p)}{\log p + X_R(p)} \right)^{1/2} L = 3 \left(\frac{D_T}{D_R} \right)^{1/2}, \quad (9)$$

which implicitly defines the length estimate $L_{T/R}$ as a function of D_T , D_R , and d (remember that $p = L/d$). Unlike L_T and L_R , the $L_{T/R}$ estimate is independent of the viscosity η . $L_{T/R}$ also depends much more weakly on the SWCNT hydrodynamic diameter d when compared to the standard LAND L_T estimate. Indeed, consider a typical estimate of the hydrodynamic diameter,⁸ $d = 5 \pm 2$ nm. Assuming a value of $d = 5$ nm when the true value is either $d = 3$ nm or $d = 7$ nm results in a systematic error of 10%–20% on L_T and L_R (on the same range as the reported accuracy of LAND⁸) but an order of magnitude less (1%–3%) on $L_{T/R}$.

B. Fluorescence autocorrelation time

The estimation of the translational diffusion coefficient from reconstructed experimental trajectories is well understood.^{8,11} On the other hand, estimating the rotational diffusion coefficient requires, on the face of it, to obtain the orientation of the SWCNT on each frame, which can only be done if the SWCNT is indeed

long enough to be visualized as a non-point emitter on a diffraction-limited imaging setup (≥ 500 nm). In that case, the length of the SWCNT could be directly measured from its image, and the analysis proposed here is moot (but see the discussion regarding optical lengths below).

One could consider using linearly polarized excitation and/or performing polarization-sensitive detection in order to obtain information about the SWCNT orientation. Here, we restrict ourselves to the experimentally simpler case of circularly polarized (or unpolarized) excitation and polarization-insensitive detection. In fact, the rotational diffusion coefficient can in this case also be indirectly inferred from fluctuations in the SWCNT fluorescence intensity. Indeed, the main cause of fluctuations in the fluorescence intensity is the change in the out-of-plane orientation of the SWCNT.

On the one hand, under circularly polarized or unpolarized excitation, the absorption cross section of the SWCNT—which can be modeled as a short dipole absorber/emitter with the transition dipole parallel to the nanotube axis—is proportional to $\sin^2 \theta$, where θ is the angle of the SWCNT relative to the optical axis [Fig. 1(a)]. On the other hand, the fraction of the fluorescence radiated in the detection cone, which is also the collected fraction of the total SWCNT fluorescence (under polarization-insensitive

detection), is proportional to

$$f(\theta) = \frac{1}{2} (\cos^2 \Theta + \cos \Theta) \left(\frac{1}{3} - \cos^2 \theta \right) + \frac{2}{3}, \quad (10)$$

where $\Theta = \arcsin(NA/n)$ is the aperture angle of the detection cone, which depends on NA , the objective numerical aperture, and n , the index of refraction of the immersion medium.¹⁴ The total observed fluorescence intensity, therefore, varies as $I(\theta) = f(\theta) \sin^2 \theta$.

This expression can be plugged into a rotational random walk simulation to generate theoretical fluorescence time traces, $I(t)$ [Fig. 1(b)]. By fitting the autocorrelation function of $I(t)$, $ACF(\Delta t) = \langle I(t)I(t + \Delta t) \rangle / \langle I(t)^2 \rangle$ [Fig. 1(c)], in the region $\exp(-2) < ACF(t) < 1$, to an exponential model $ACF(\Delta t) = \exp(-\Delta t/\tau_{FA})$, we find that the fluorescence autocorrelation time τ_{FA} satisfies

$$\tau_{FA} \approx 0.168/D_R. \quad (11)$$

In other words, the rotational diffusion coefficient can be obtained from the fluorescence autocorrelation time by the simple relation $D_R = 0.168/\tau_{FA}$.

The translational diffusion of SWCNT along the optical axis (in and out of the depth of the field) may appear to also contribute to fluctuations in fluorescence intensity. However, the mean time over which a SWCNT diffuses over the depth of field (DOF) ($\approx 1 \mu\text{m}$) is $\tau_{DOF} \approx \text{DOF}^2/2D_T$; therefore, we have

$$\frac{\tau_{DOF}}{\tau_{FA}} \approx 54 \left(\frac{\text{DOF}}{L} \right)^2 \gg 1. \quad (12)$$

Hence, the fluctuations in fluorescence intensity due to the translational diffusion of the SWCNT along the optical axis occur over a much longer time scale than rotational diffusion and can be neglected here.

III. ANALYSIS AND DISCUSSION

In order to validate the L_R and $L_{T/R}$ methods and to compare their performance with the L_T (LAND) method, we recorded and analyzed 5 movies, of 8000 frames each, of (6,5) SWCNTs diffusing in a 2:1 v/v glycerol–water mixture (tabulated viscosity:¹⁹ $\eta = 20.6$ mPa s). The SWCNTs were excited at the S_{22} transition with a 568 nm laser. Imaging was performed on a high-speed, near-infrared fluorescence microscopy setup [Fig. 2(a); Methods] at a frame rate of 125 fps. The range of interest for SWCNT lengths goes from $0.5 \mu\text{m}$ (the shortest optically resolvable length) to $2.5 \mu\text{m}$ (the longest SWCNTs expected in the sample). For such lengths, the predicted fluorescence autocorrelation time under our experimental conditions goes from 30 ms to 2400 ms, i.e., from 3.5 to 300 frames; the fast frame rate used was chosen in order to be able to observe the intensity fluctuations of the shortest optically resolvable SWCNTs.

Custom fitting and linking routines were used to localize long nanotubes (by fitting them to straight segments, the center of which were used as SWCNT positions) and reconstruct trajectories

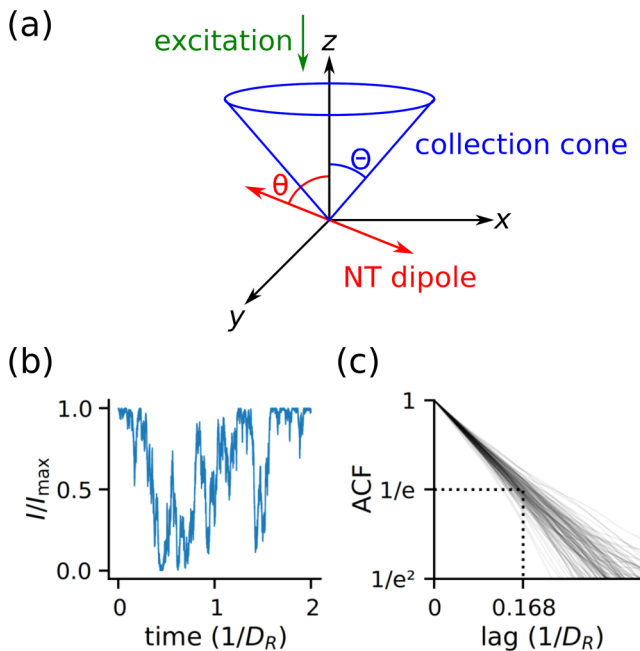


FIG. 1. (a) Experimental geometry. The excitation and fluorescence collection take place along the z axis. (b) Sample simulated fluorescence intensity trace. (c) Fluorescence autocorrelation functions of 100 simulated traces (semi-log y scale). In (b) and (c), times are in units of $1/D_R$, the natural characteristic timescale for rotational diffusion.

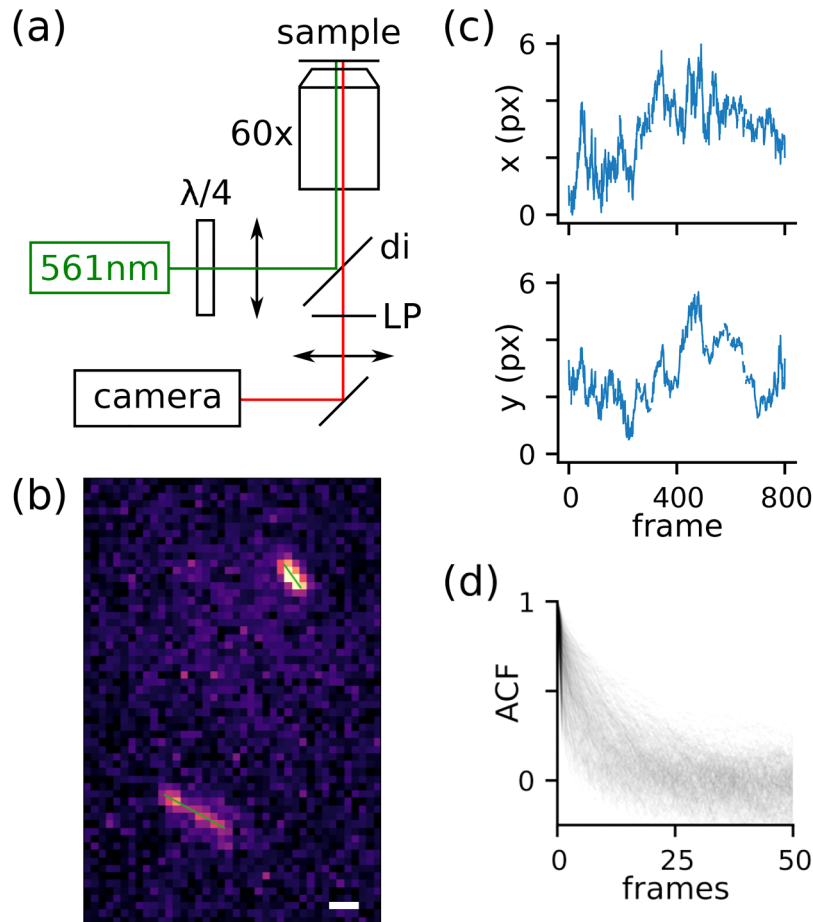


FIG. 2. (a) Microscopy setup for excitation and imaging of (6,5) SWCNTs. 561 nm, excitation laser; $\lambda/4$, quarter-wave plate; di, 875 nm long-pass dichroic mirror; and LP, 900 nm long-pass emission filter. (b) Sample frame, including two SWCNTs (fitted to green segments). Scale bar, $1\mu\text{m}$. (c) Sample SWCNT position (x vs t , y vs t) traces. (d) Fluorescence autocorrelation functions of all trajectories in the dataset.

[Figs. 2(b) and 2(c)]. Trajectories with less than 100 localizations were discarded, leaving $N = 825$ trajectories.

Translational diffusion analysis was performed following standard single-particle tracking methodologies. When required, sample drift was estimated from the mean displacement of all nanotubes from each frame to the next and subtracted from all trajectories.¹³

The fluorescence autocorrelation function $\text{ACF}(\Delta t)$ was computed for each trajectory and fitted, as for the simulations, to an exponential model. In the presence of uncorrelated experimental noise ($I_{\text{exp}}(t) = I(t) + \epsilon(t)$), the experimental autocorrelation function is decreased by a constant multiplicative factor at all nonzero lags,

$$\text{ACF}_{\text{exp}}(\Delta t) = \begin{cases} \text{ACF}(0) (=1) & \text{if } \Delta t = 0, \\ \frac{\langle I^2 \rangle}{\langle I^2 \rangle + \langle \epsilon^2 \rangle} \text{ACF}(\Delta t) & \text{if } \Delta t \neq 0. \end{cases} \quad (13)$$

Therefore, experimental noise was taken into account by fitting this additional factor ($\langle I^2 \rangle / (\langle I^2 \rangle + \langle \epsilon^2 \rangle)$).

For 18 of the 825 trajectories (2%), the value of the autocorrelation function at the first lag was less than $\exp(-2)$. In these cases,

we deemed the fluctuations to be too noisy or too fast to be resolved at the used frame rate. For the other 807 trajectories, for which the fluorescence autocorrelation time, and thus the rotational diffusion coefficient, could be estimated, we computed the three different diffusion-based length estimates: L_T , purely from the translational diffusion coefficient [i.e., the LAND estimate; Eq. (4)]; L_R , purely from the rotational diffusion coefficient [Eq. (7)]; and $L_{T/R}$, by combining translational and rotational diffusion coefficients [Eq. (9)]. The L_T and L_R estimates depend on the solution viscosity and the SWCNT hydrodynamic diameter; here, we assumed that the solution viscosity matched its tabulated value ($\eta = 20.6 \text{ mPa s}$) and used a hydrodynamic diameter of $d = 5 \pm 2 \text{ nm}$. No thin-film correction was applied to the solution viscosity, as imaging was performed at the center of a relatively thick, $\sim 60 \mu\text{m}$ chamber. The $L_{T/R}$ estimate is fully independent of η and only depends very weakly on d .

The three diffusional methods yield overall distributions of SWCNT lengths with similar medians but with different spreads (Fig. 3). Because L_T and L_R are computed from essentially independent data sources (SWCNT positions for L_T and SWCNT intensities for L_R), their consistency validates the accuracy of the

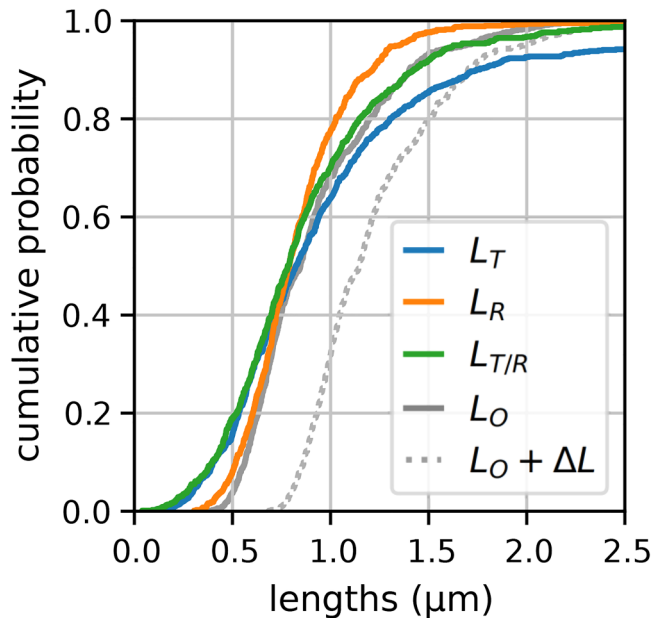


FIG. 3. Cumulative probability distributions of SWCNT lengths estimated from diffusion coefficients (L_T , translational diffusion; L_R , rotational diffusion; and $L_{T/R}$, translational and rotational diffusion) and optically (L_O , without correction for exciton diffusion and $L_O + \Delta L$, with correction for exciton diffusion). L_T , L_R , and $L_{T/R}$ yield distributions with similar medians but different spreads. Coincidentally, L_O is also consistent with them but not $L_O + \Delta L$. Note that the full L_T distribution extends well beyond $5\mu\text{m}$, which is indicative of large estimation errors arising from this case.

measured distributions. Some differences, however, are present between the distributions: L_T is the widest, L_R is the sharpest, and $L_{T/R}$ is intermediate. The wider distribution of L_T (i.e., of D_T) may arise from inaccurate localizations—occurring, in particular, when SWCNTs move partially out of focus in our thick sample, resulting in only one end of the SWCNT being taken into account by the localization fitter—or from incomplete drift correction. Because such problems do not change the total collected fluorescence intensity, they do not affect D_R , which solely relies on SWCNT detection and trajectory reconstruction; therefore, L_R is a more accurate and sharper length estimate. $L_{T/R}$ is computed as a combination of D_T and D_R and is, therefore, affected to an intermediate degree by mislocalization and drift; any improvement to the estimation of D_T would not only improve the precision of L_T (assuming well-known η and d), but also the precision of $L_{T/R}$ (independently of η and d) as well.

Another length estimate that we considered for comparison with L_T , L_R , and $L_{T/R}$ is the direct measurement of the apparent SWCNT length on the movie images. Specifically, on a given frame, the apparent length L of a SWCNT depends on its angle θ relative to the optical axis, $L = L_O \sin \theta$ [Fig. 1(a)], where L_O is the “optical” length of the nanotube when lying in the sample plane. The probability density of observing a certain length L (only considering the SWCNT orientation randomness while ignoring the

measurement error) is thus

$$p(L) \propto \sin \theta \frac{d\theta}{dL} = \frac{\tan \theta}{L_O}, \quad (14)$$

which diverges at $\theta = \pi/2$; i.e., $L = L_O$. The experimentally observed distribution of lengths along a trajectory is affected by finite sampling, measurement errors, and worse detection efficiency for nanotubes aligned with the optical axis—which appear both shorter and dimmer—but is indeed asymmetric (Fig. 4) and is peaked at the true length L_O . Therefore, the nanotube length must be estimated as the mode of the distribution of observed SWCNT lengths along the trajectory. We used the half-sample mode method²³ to obtain a non-parametric estimator of the mode of a finite sample. Finally, in order to take into account the SWCNT dark ends arising from exciton diffusion, a correction term $\Delta L \sim 2 \times 150 \text{ nm}$ needs to be added to this optical estimate.

Strikingly, we find that the distribution of optical lengths including exciton diffusion correction ($L_O + \Delta L$) is shifted by $\sim 300 \text{ nm}$ relative to all diffusional length distributions (Fig. 3). (By coincidence, the uncorrected optical lengths (L_O) match the diffusional length distributions relatively well.) A possible reason for this discrepancy is the poor definition for the “ends” of the SWCNT in an optical image: at the SWCNT extremities, the fluorescence does not decrease sharply but continuously over one or two pixels [Fig. 2(b)], making sub-pixel determination of SWCNT

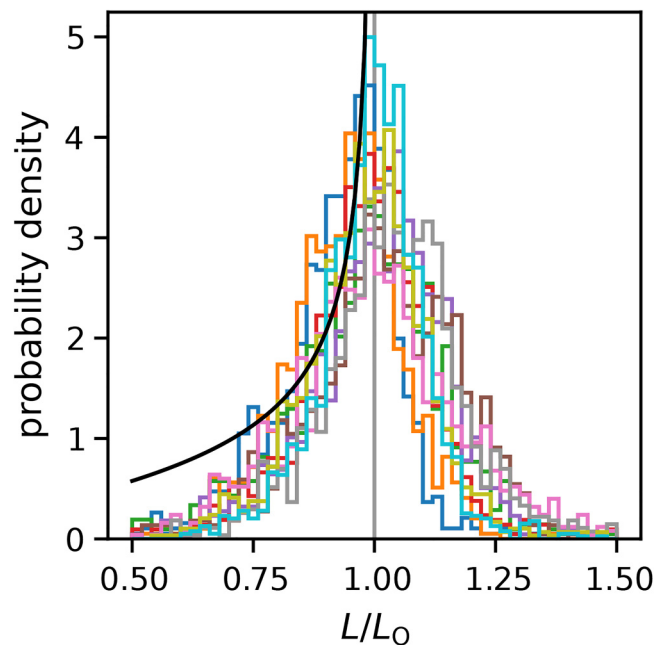


FIG. 4. Distribution of lengths L measured on each frame of the trajectory, each normalized to its own half-sample mode L_O , for the ten longest trajectories in the dataset and (in black) theoretical distribution only considering geometrical effects and ignoring measurement inaccuracies described in the text. The asymmetry of the distributions is apparent.

length impossible in the absence of a detailed model for this decrease (the model also needs to take into account other sources of fluorescence decrease, such as partial defocus). Therefore, optical length measurements should be considered with caution, especially for quickly diffusing SWCNTs, when sub-pixel (≈ 250 nm) accuracy is required.

IV. CONCLUSION

Here, we have described a simple method to improve the robustness of the SWCNT lengths obtained from a LAND analysis. The fluctuations in the fluorescence intensity of the SWCNT along its trajectory are directly correlated with the SWCNT rotational diffusion coefficient; by themselves, they yield a good estimate of the SWCNT length, which is fully independent of drift correction and other sources of localization error. As this estimate still depends on the accurate knowledge of the solution viscosity and of the SWCNT hydrodynamic diameter, we propose yet another approach: we combine the fluorescence fluctuation analysis together with the translational diffusion analysis (which does depend on accurate localization) in order to obtain a length estimate that is fully independent of viscosity and nearly independent of the SWCNT hydrodynamic diameter. It should be noted that the method we described is more generally applicable to any linear fluorescent nano-object (e.g., nanowires shorter than their persistence length), as long as they exhibit non-isotropic fluorescence excitation and/or emission; if excitation and emission do not arise from dipoles aligned with the object, Eqs. (10) and (11) simply need to be adjusted accordingly. Therefore, we foresee that this method will be a valuable improvement over the standard LAND approach for the high-throughput estimation of the lengths of SWCNT and other linear nano-objects, required for many applications.

V. METHODS

A. Sample preparation

SWCNTs were prepared as previously described.²⁴ HiPco-synthesized nanotubes (batch no. 195.7, Rice University) were mixed in 1% w/v NaDOC in D₂O, homogenized in a shear mixer at 19 000 rpm for 10 min, and tip sonicated at 20 W–25 W power for 8 min in a cold water bath. SWCNT bundles and impurities were precipitated by ultracentrifugation at $144\,000 \times g$ for 4 h.

A 1.5 μ l drop of SWCNT suspended in a 2:1 v/v glycerol–water mixture was pressed between two #1.5 coverslips, surrounded by vacuum grease, which formed a sealant preventing evaporation and convection. The thickness of the solution between the coverslips was ≈ 60 μ m, and imaging was performed close to the midpoint between the coverslips in order to minimize boundary effects.¹⁶

B. Single SWCNT fluorescence video microscopy

Imaging was performed on an inverted microscope (Nikon). (6,5) SWCNTs were excited at the S_{22} transition with a 568 nm laser (Coherent Sapphire). A quarter-wave plate was used to obtain a circularly polarized excitation beam. A long-pass dichroic mirror (FF875-Di01, Semrock) was used on the excitation path and a long-pass emission filter (ET900LP, Chroma) on the collection path.

Images were collected through a water immersion 60 \times objective (NA 1.27, Nikon) on an InGaAs camera (C-RED2, First Light Imaging) at 125 frames/s.

C. Analysis

Data analysis (localization, trajectory reconstruction, LAND, fluorescence autocorrelation analysis) and simulations were performed using custom implementations of the described algorithms in the Python and C++ programming languages.

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DATA AVAILABILITY

The data that support the findings of this study are available from the corresponding author upon reasonable request.

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